NASA Conference Publication 3158 Part 2

# Sixteenth International Laser Radar Conference



Abstracts of papers presented at a conference and held at the Massachusetts Institute of Technology Cambridge, Massachusetts July 20–24, 1992

AMS USAF OSA NASA

# Atmospheric Measurements Using the LAMP Lidar during the LADIMAS Campaign

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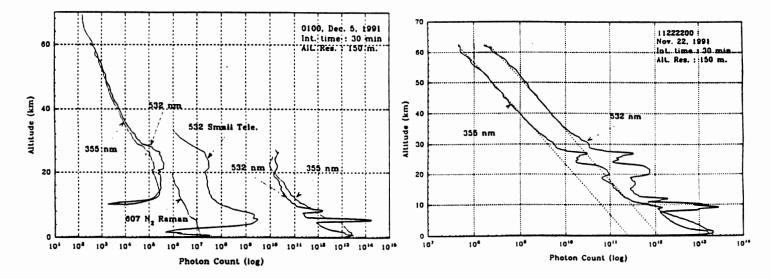
## SUMMARY

The results of the <u>LA</u>titudinal <u>DI</u>stribution of <u>Middle A</u>tmosphere <u>S</u>tructure (LADIMAS) experiment have provided a unique data set to improve our understanding of the middle atmosphere. The project included ship-board and rocket range coordinated measurements between 70N to 65S to study the structure, dynamics and chemistry of the atmosphere. Results on important dynamical processes, such as gravity waves, tidal components, as well as the formation of the layers of meteoric ion and neutral species, have been obtained with lidar, digisonde, microwave radiometer, and spectrometers. The cooperative study of the atmosphere was undertaken by researchers from several laboratories, including Penn State University, University Bonn, University Wuppertal, Lowell University, and others. Several of the parameters studied have never been measured before over such a wide range of latitudes. Instruments were assembled aboard the German research vessel RV POLARSTERN while this vessel was sailing from the Arctic to the Antarctic seas between October 8, 1991 and January 2, 1992. This paper presents an introduction to the data gathered by the PSU investigation with the LAMP lidar.

## MEASUREMENTS

The LAMP (Lidar Atmospheric Measurements Program) instrument is an advanced laser remote measurement sensor which has been built-up during 1990-1991. The design follows the progressive development of our two previous lidar designs [1,2]. This instrument extends the measurement range to cover the troposphere as well as the stratosphere and mesosphere, using the molecular and Raman scatter signals at several wavelengths to determine the profile distributions of density, temperature, extinction, particle back-scatter, and water vapor concentration. The instrument uses a high power Nd:YAG laser with an output of 1.5 J/pulse at 20 Hz. The fundamental wavelength is doubled to obtain 600 mJ pulses at 532 nm and mixed to obtain 250 mJ pulses at 355 nm. The transmitter, receiver, detector, and data system combination have been integrated into a standard shipping container, which serves as a field laboratory. The primary receiver is a 41 cm diameter Cassegrain telescope. The measurements of the back-scatter radiation are made at the fundamental wavelengths of 532 and 355 nm with several different detectors in order to cover the dynamic range. Figure 1 shows an example of the raw lidar signal, corrected for R<sup>2</sup> dependance, which is typical of the signals measured on several of the data channels. The low altitude channels for 532 and 355 nm receive about 5% of the collected intensity and the measurement is made in analog mode with an A/D converter at 10 MHz (15 meter altitude steps) with 12 bit resolution. The high altitude channels are mechanically shuttered below 15 km to prevent the PMT's from being saturated. The high altitude channels and the Raman channels for  $N_2$ , at 607 nm, and for H<sub>2</sub>O, at 660 nm, use photon counting detectors, with range bins of 500 nanoseconds (75 meter altitude steps). A smaller telescope, 20 cm diameter, was used for independent

measurements, most frequently at the 532 nm wavelength. In Figure 2, the profiles of the low and high altitude channels have been overlapped to provide continuous profiles from 200 meters to 80 km. The back-scatter and extinction associated with the stratospheric aerosols, clouds and the boundary layer can be readily observed in the profiles of these two wavelengths. Notice that the scattering ratio of the 532 nm compared to the 355 nm changes significantly with the changing size of the particle scatterers. When the stratospheric aerosol scattering intensities are compared to those for the tropospheric clouds, the change in extinction and back-scatter cross-section with particle size is obvious.



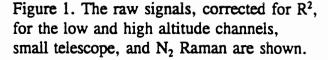
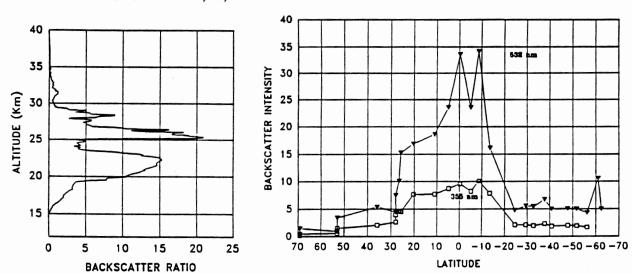


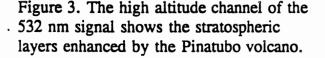
Figure 2. Low and high altitude channels are joined to form continuous profiles.

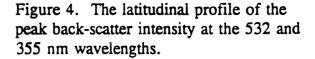
The initial data of LADIMAS, for the LAMP instrument, were gathered at Andoya Rocket Range, Norway. On the leg between Tromso, Norway, and Bremerhaven, Germany, the operational testing of the instrument on the ship was completed. Measurements were made on each clear night, and on some occasions, the measurements were made below and into the clouds. The measurements included high and low altitude channels for the 532 and 355 nm wavelengths, Raman shifted N<sub>2</sub> at 607 nm, Raman shifted H<sub>2</sub>O at 660 nm, and 532 nm measurements from a second telescope simultaneously recorded. The variation in the profile, see Figures 1 and 2, near 25 km is due to particle scattering. One of the more striking features observed by the LADIMAS instruments is the lower stratospheric aerosol and particle layer. The high altitude signal, above about 30 km, can be easily analyzed to provide density and temperature profiles [3]. The two-color approach [1, 2] allows the detection of the molecular and particle components. Note that the particle scattering relative intensity is much stronger for the 532 than for the 355 signals. The cross-section for the molecular scatterers is much larger at 355 nm, while the particle cross-section may not differ significantly between the two wavelengths [for example, see 4]. Figure 3 shows the

measured signals of the 355 and 532 nm channels, together with the profiles of the aerosol scattering ratio to the molecular scattering, in this case, unity has been subtracted. Figure 4 shows the latitudinal plot of the scattering ratio for the 355 and 532 nm wavelengths. The strong variation in the scattering ratio as a function of latitude may be a result of the recent Pinatubo volcano eruption which transported dust to stratospheric heights [see 5]. The two color lidar shows a strong difference in relative back-scatter intensity from the stratospheric aerosols. The extinction due to the layers is obvious in the profiles.

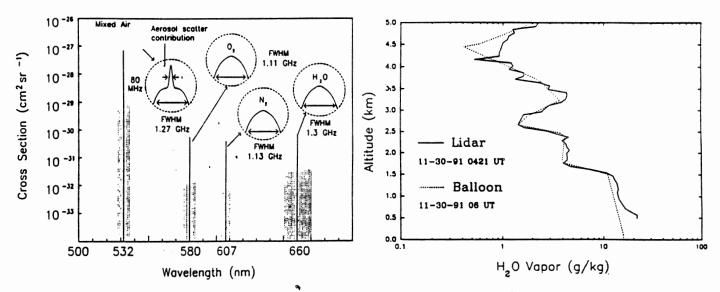








At tropospheric altitudes, the Raman  $N_2$  profile together with the two-color back-scatter should allow the separation of the extinction, back-scatter due to particles and the molecular back-scatter signals. The advantage in using the Raman signals in the lower atmosphere is clear from the profiles shown above. Figure 5 shows a representation of the spectral signatures which would be expected from the back-scatter due to the 532 nm laser radiation in an atmospheric volume (after Inaba and Kobayasi [6]). The laser is injection seeded to give a line-width of about 80 MHz and thus the particle back-scatter is of that spectral width, while the molecular peaks are broadened by the thermal Doppler spreading. The vibrational Raman scattering peaks are shown for  $O_2$ ,  $N_2$  and  $H_2O$ . Each of the peaks is also broadened at their base due to the rotational splitting of each vibrational state. Only the first Stokes vibrational states are indicated. The figure indicates the large cross-section difference in the processes involved. The Raman H<sub>2</sub>O signal ratio to the Raman N<sub>2</sub> signal provides a good measure of the water vapor concentration. Figure 6 shows the profiles of the water vapor concentration at two of the times when rawinsonde balloon data were available for comparison. The previous work of Melfi [7] has shown the power of the Raman technique for obtaining water vapor measurements. The results gathered here have provided a data base to study the marine boundary layer.



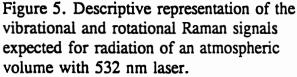


Figure 6. Examples of the water vapor concentration obtained from the Raman signals.

### ACKNOWLEDGEMENTS

The effort to prepare the LAMP instrument has been supported by PSU/ARL project initiation funds, PSU College of Engineering, Lidar Atmospheric Profiler program for the US Navy, and the National Science Foundation's CEDAR (Coupling Energetics and Dynamics of Atmospheric Regions) Program. The measurements on the RV POLARSTERN were made possible by invitation of the Alfred-Wegener-Institut which is gratefully acknowledged. The long term collaborative efforts with Professors U. von Zahn and D. Offermann have made these investigations possible. The efforts of D. Sipler, C. Croskey, J.D. Mathews, D.E. Upshaw, D.W. Machuga, S. Maruvada, S. McKinley, G. Evanisko and G. Pancoast have contributed much to the success of the project.

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